Non Class Diagrams

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High Level System Overview

1. Unity sends timing information to Project Hollow Point.

2. Project Hollow Point Formats data for use in the Wrapper, as well as controlling when Bullet Physics Updates.

3. Wrapper sends data into the Bullet Physics Library DLLs so it can be processed.

4. Project Hollow Point takes update information and broadcast after partial Physics Updated and after fixed Update Messages.

5. Project Hollow Point converts back to Unity 3D's data format for renderering



Simulation Overview



General Update Workflow



Timing Diagram Update/ Fixed Update



Rigid Body Add Impulse



- 1. BP_RigidBody.AddImpulse(Unity3D.Vector3 impulse) invoked
- 2. If Rigid Body is in Physics world space Set
 __rigidBody =
 BulletSharp.RigidBody.ApplyImpulse(impulse.ToB
 ullet())
- 3. Return

2.a. If Rigid Body is not in physics world space return

This is pretty much the outline for all impulse, torque, and force modifications to the Rigid Body, just change the BulletSharp.RigidBody method invoked

Primitive Creation

- 1. CreateNew(Unity3D.Vector3 pos, Unity3d.Quaternion rot) invoked
- 2. Create new Unity3D.GameObject
- 3. Add BP_Primitive() to new Game object//using the actual concrete class
- 4. buildMesh() invoked on new primitive
- 5. Assign name to Game Object
- 6. Return Game Object

Build Mesh

- 1. Get component sharedMesh and set to BP_PrimitiveSettings.Build()
- 2. Get Component with type equal to the shape being built
- 3. Set dimensions form the mesh settings to the shape

Collision Object Notes

Collision Objects are added to the current active physics world through the update manager when the collision object is enabled. This done via an event handler and delegate functions.

Collision objects are removed as listeners when they are disabled

Each object also has the ability to broadcast messages to child components when the persistent manifold is visited and when it is finished, this is to improve timing control.